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The influence of partial occlusion on shape recognition

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PERCEPTION

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The influence of partial occlusion on shape recognition

Gunnar Schmidtmann



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AVA Christmas Meeting 2020

Background



“...information is concentrated along contours at those points on a contour at which its direction changes most rapidly...”

“Common objects may be represented with great economy, and fairly striking fidelity, by copying the points at which their contours change direction maximally, and then connecting these points appropriately with a straightedge.”



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Attneave, F. (1954). Some informational aspects of visual perception. *Psychological review*, 61(3), 183–193.

Previous work

SCIENTIFIC REPORTS

OPEN

Shape recognition: convexities, concavities and things in between

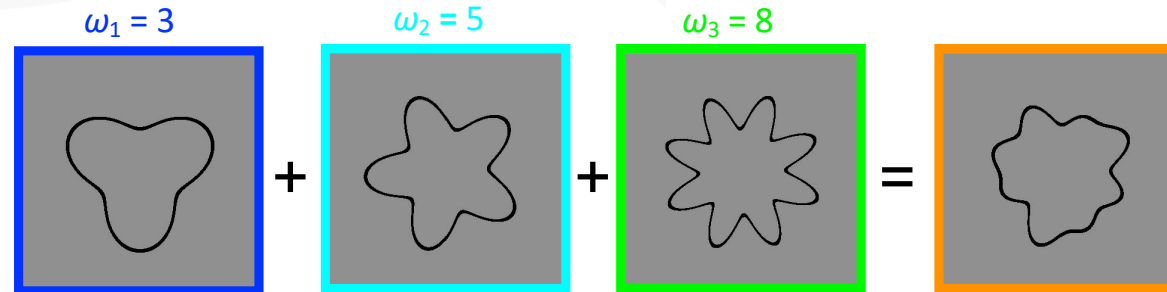
Gunnar Schmidtmann, Ben J. Jennings & Frederick A. A. Kingdom



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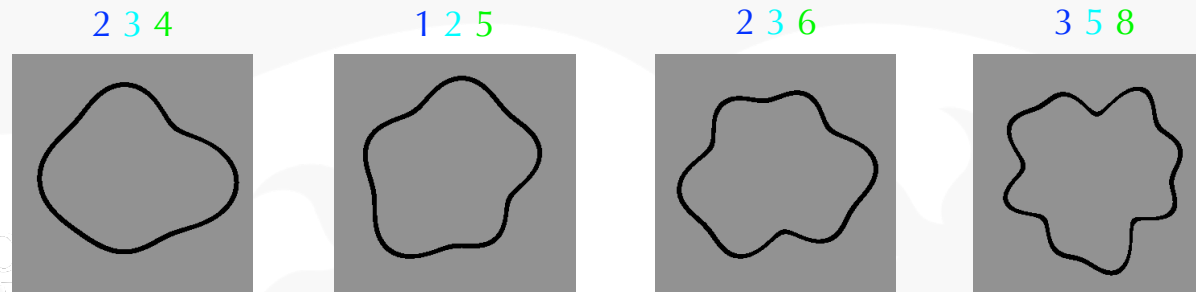
Stimuli

compound radial frequency patterns



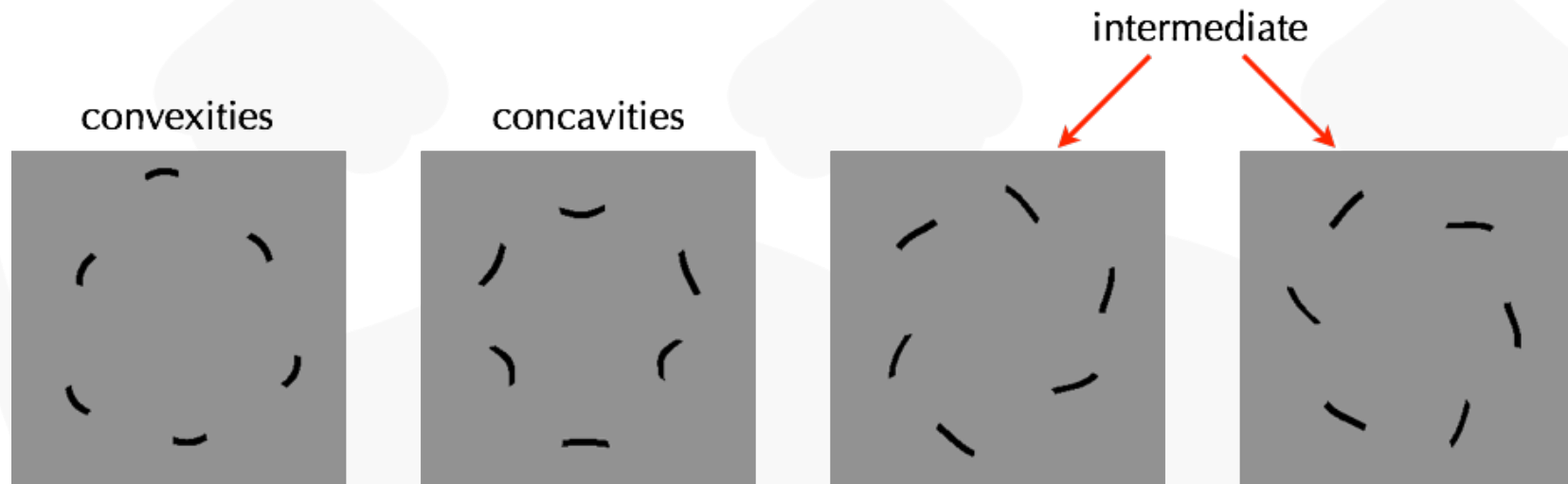
$$RF_{compound} = r_{mean}(1 + A_1 \sin(\omega_1 \theta + \varphi_1) + A_2 \sin(\omega_2 \theta + \varphi_2) + A_3 \sin(\omega_3 \theta + \varphi_3))$$

- r_{mean} : mean radius of underlying circle (=100 Pixel)
- A : modulation amplitude (=0.1)
- ω_1 : radial frequency
- θ : polar angle
- φ_1 : phase / orientation (random)



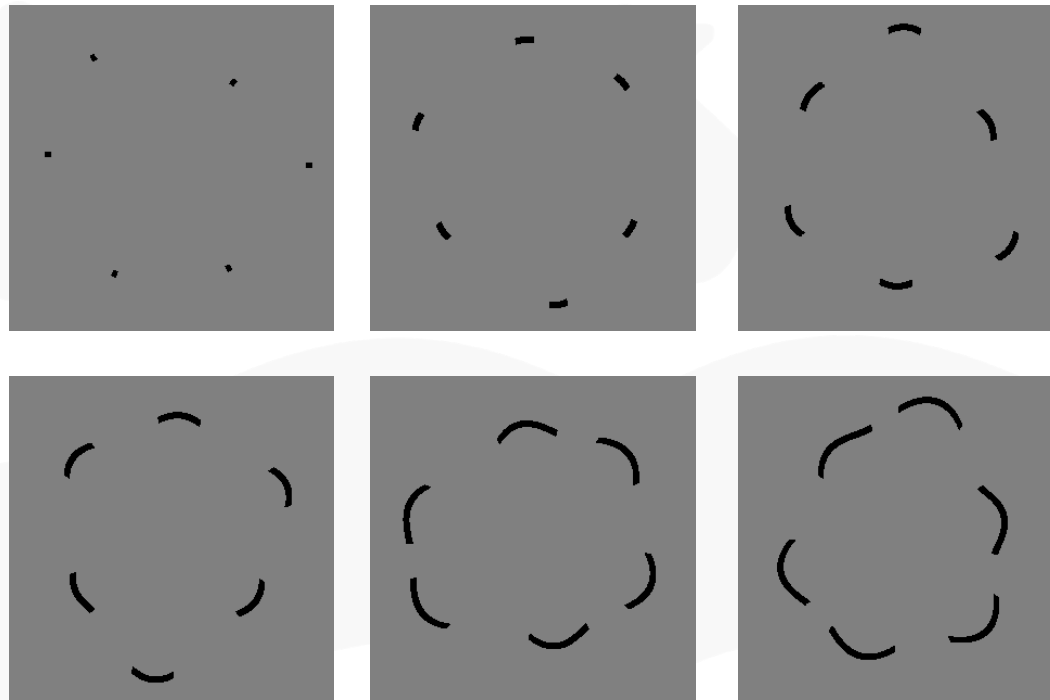
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Stimuli



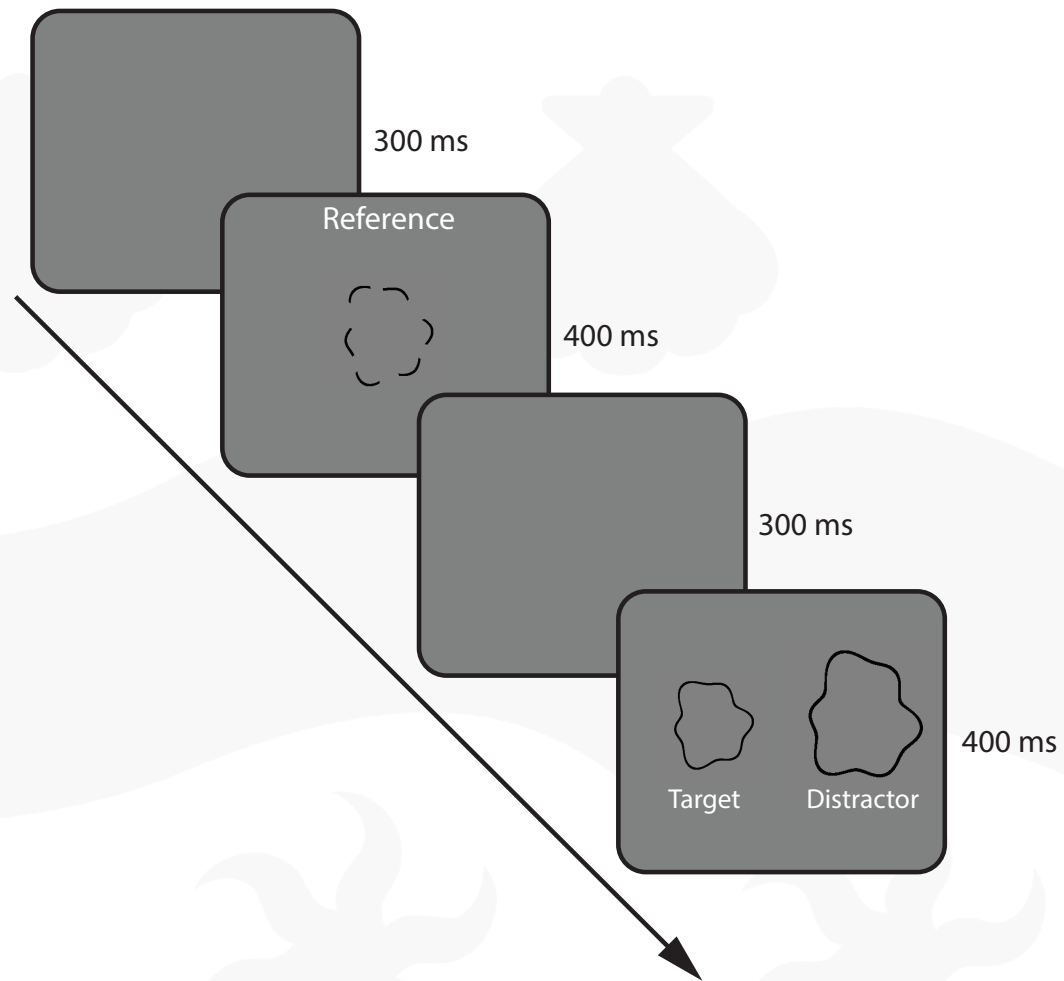
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Stimuli

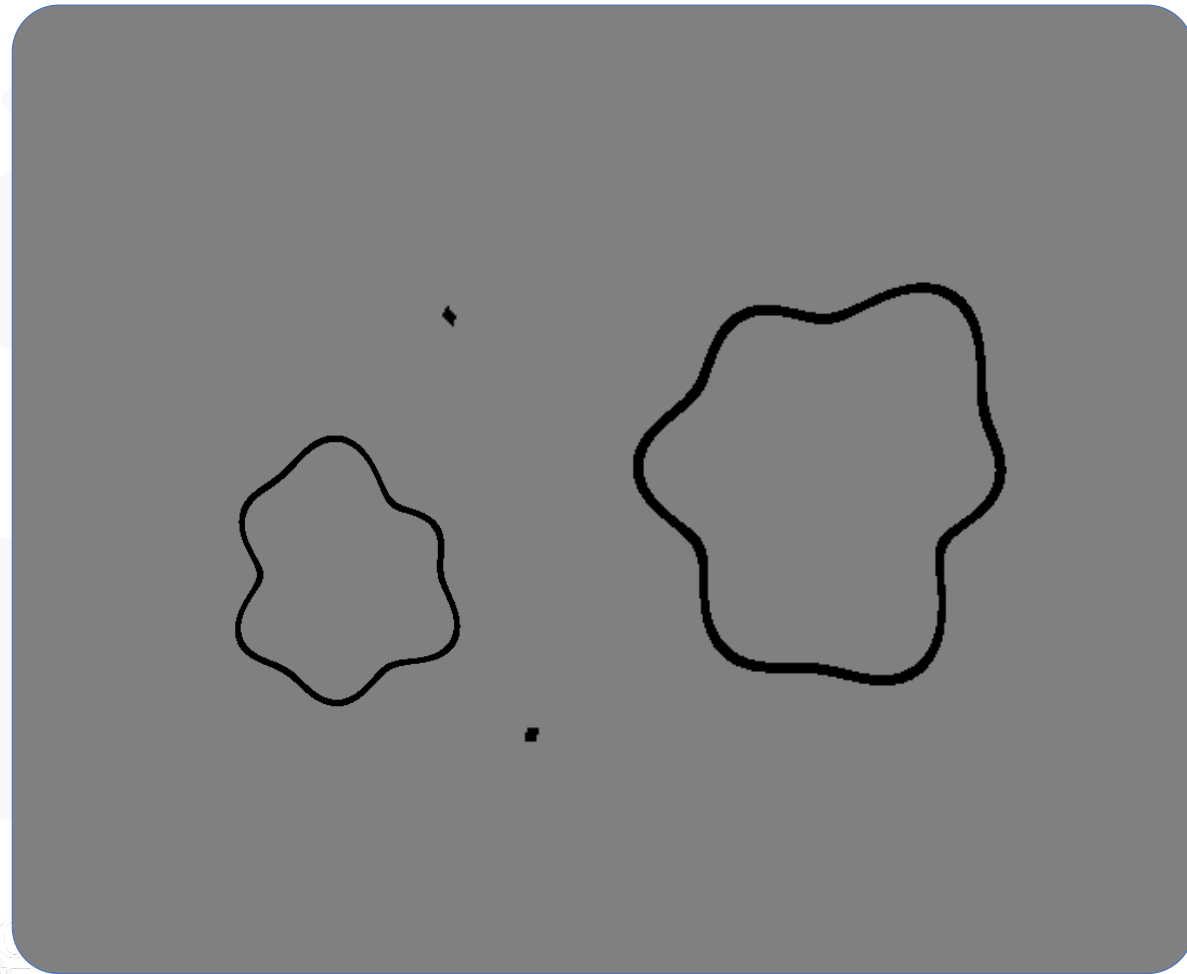


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Paradigm

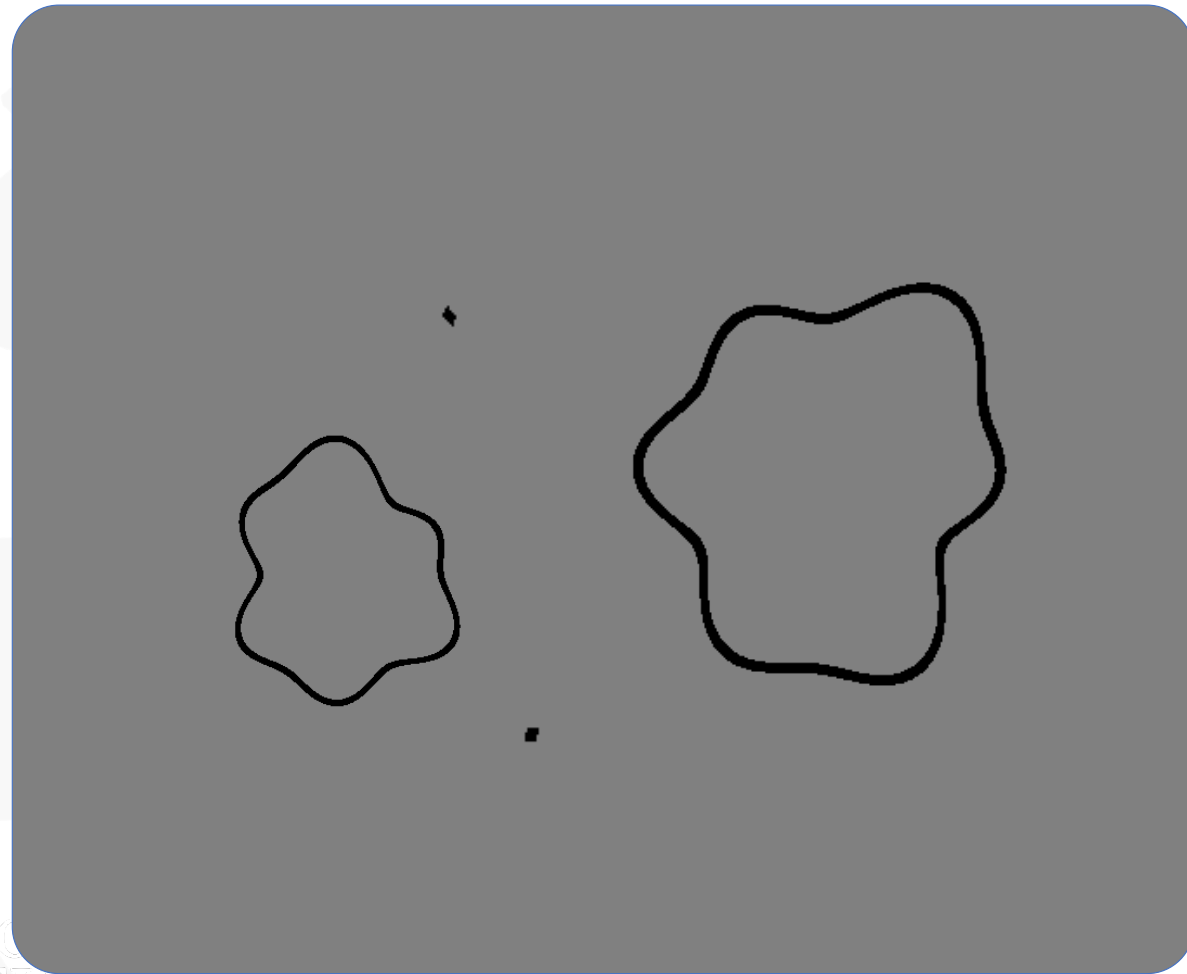


Demo



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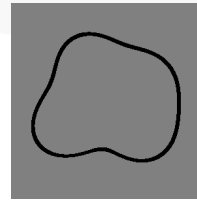
Demo



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Results

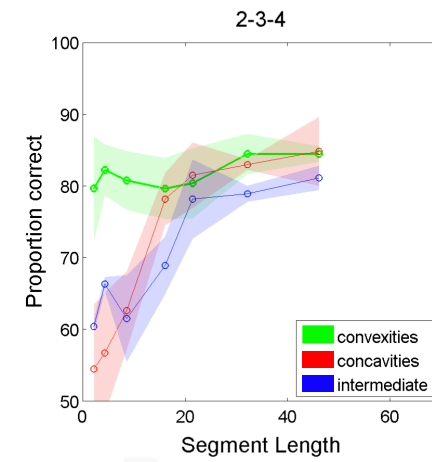
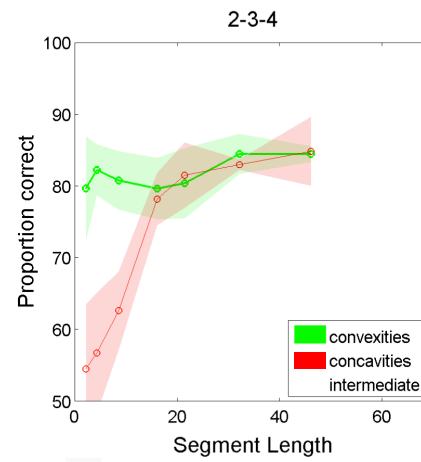
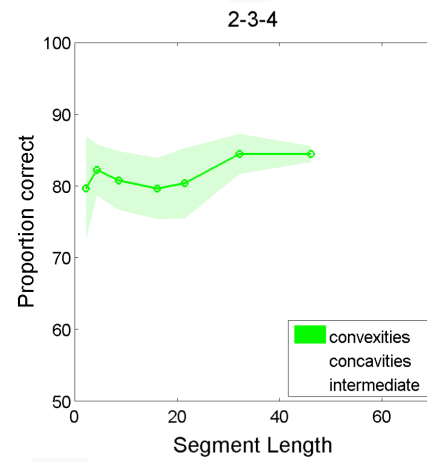
2-3-4



convexities

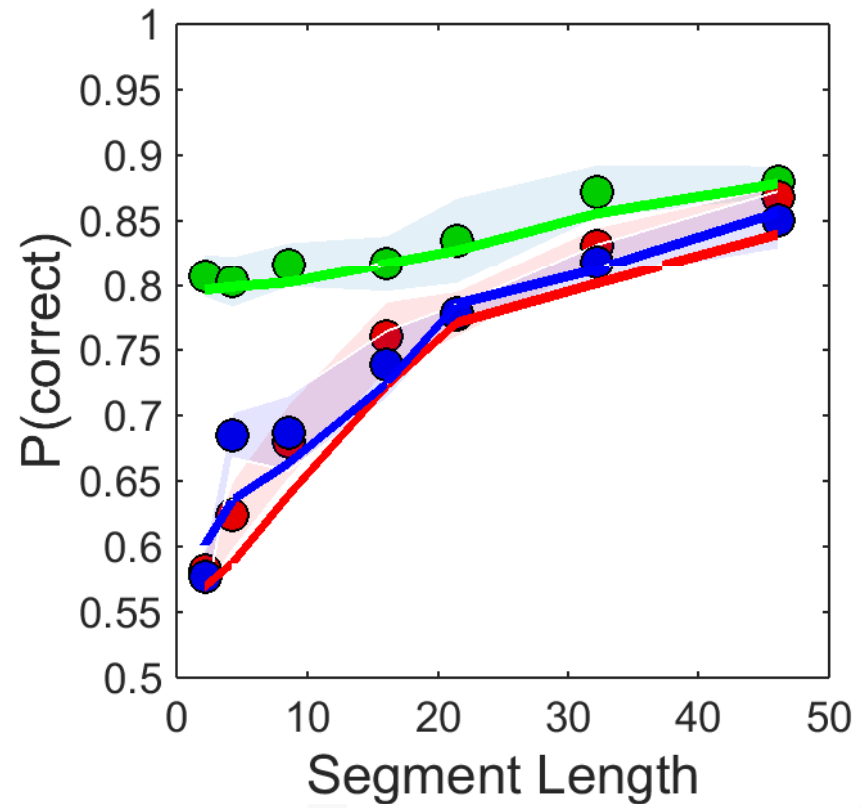
concavities

intermediate

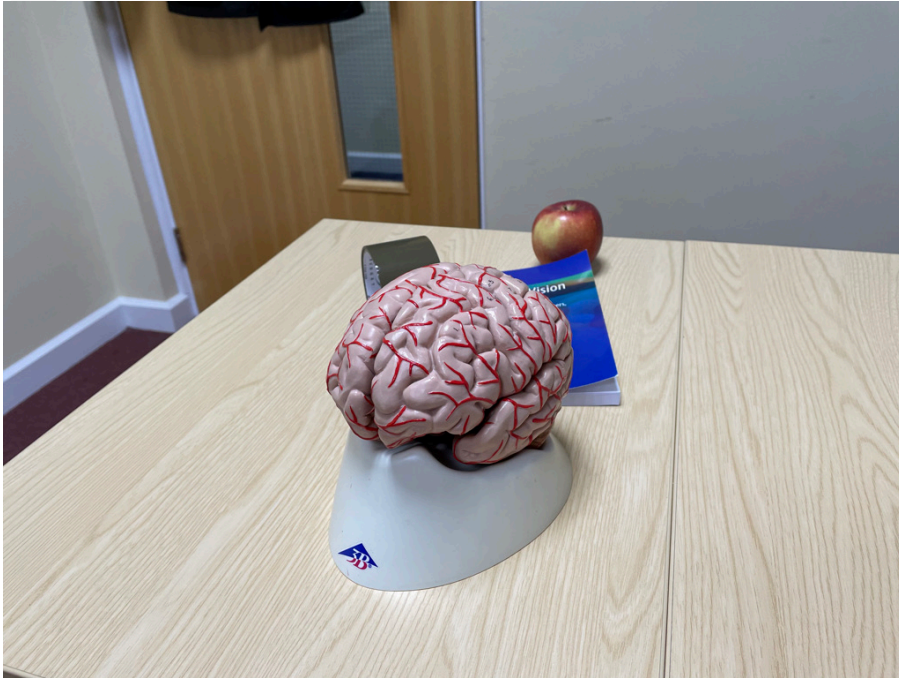


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Model Results

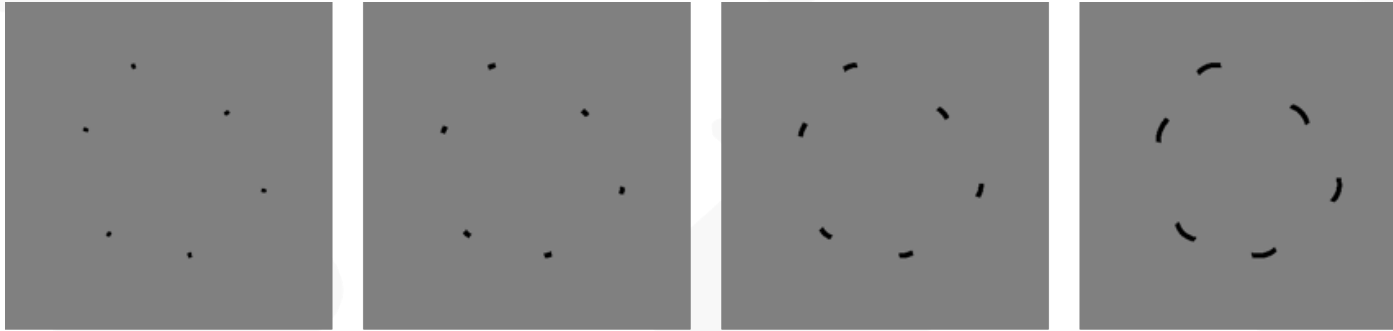


New Experiment - Partial Occlusion

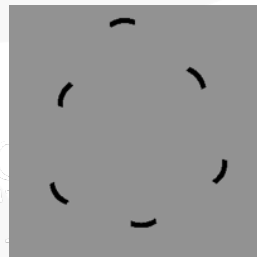


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Stimuli



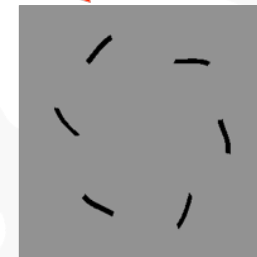
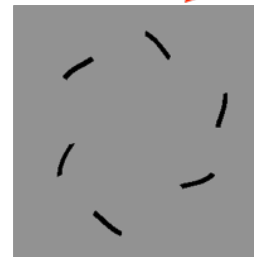
convexities



concavities



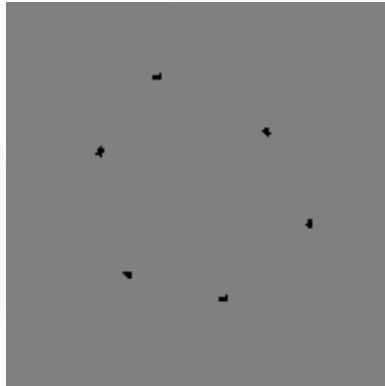
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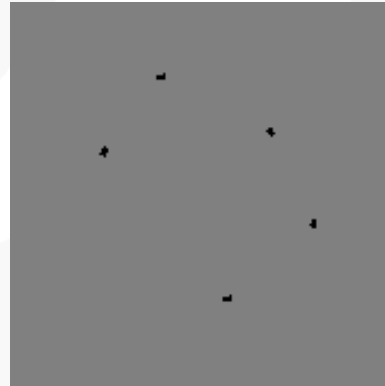
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Partial Occlusion

No occlusion



16.7% occlusion



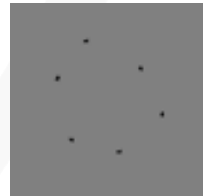
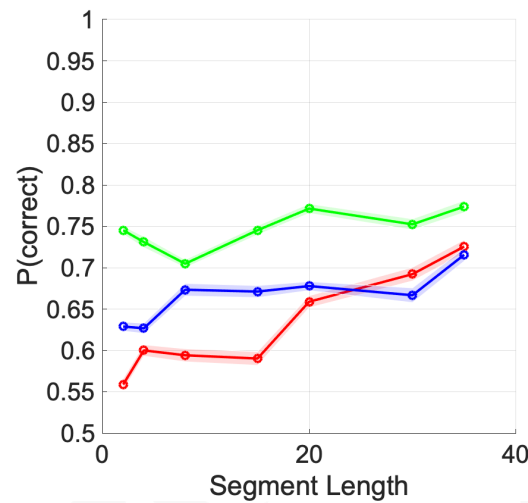
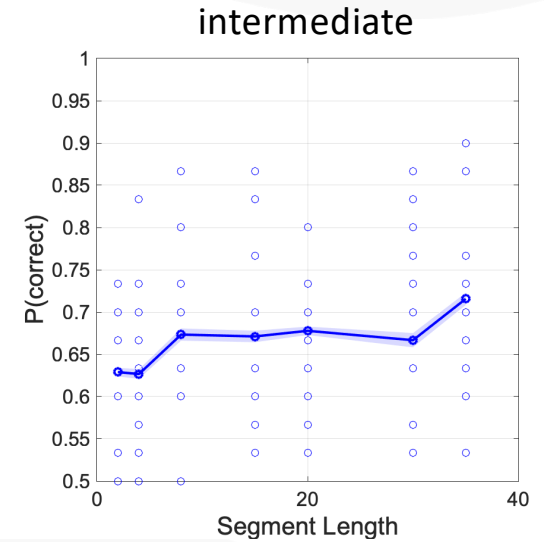
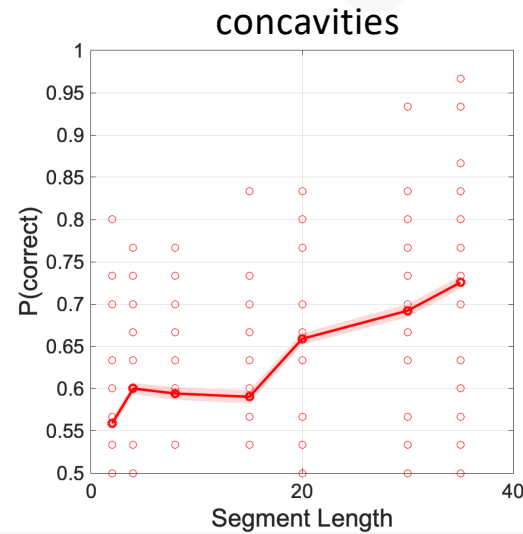
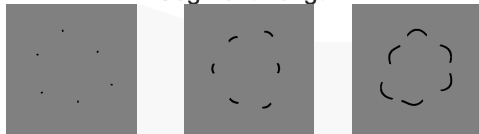
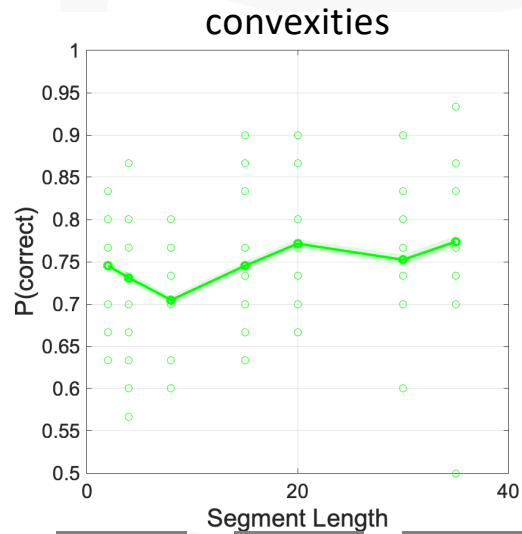
33% occlusion



50% occlusion



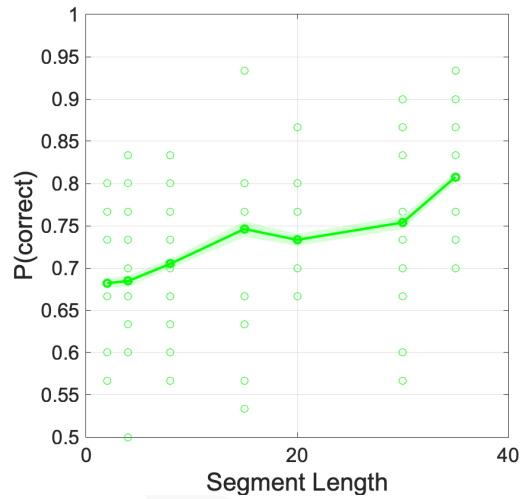
Results – no occlusion



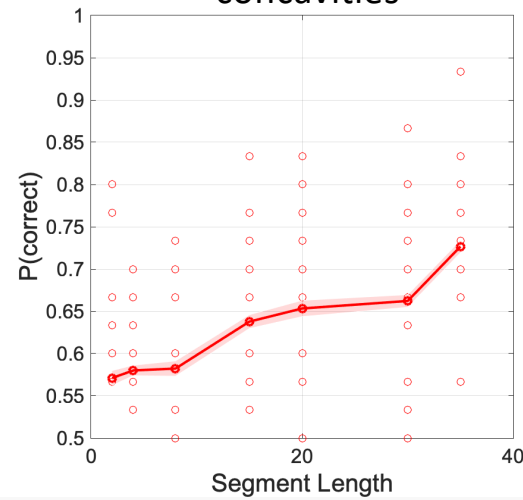
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Results – 16.7% occlusion

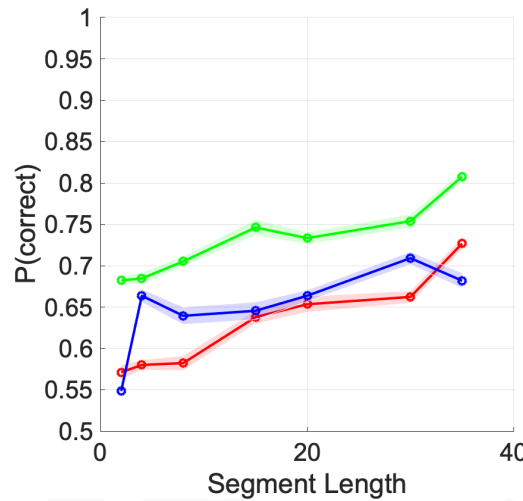
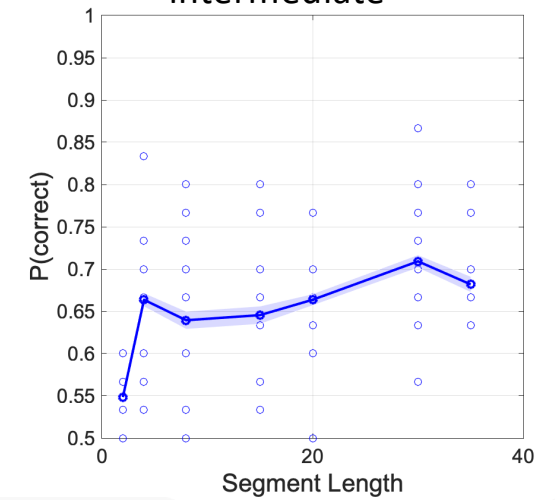
convexities



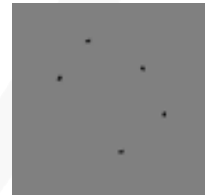
concavities



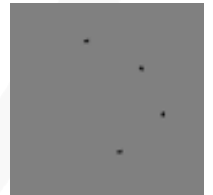
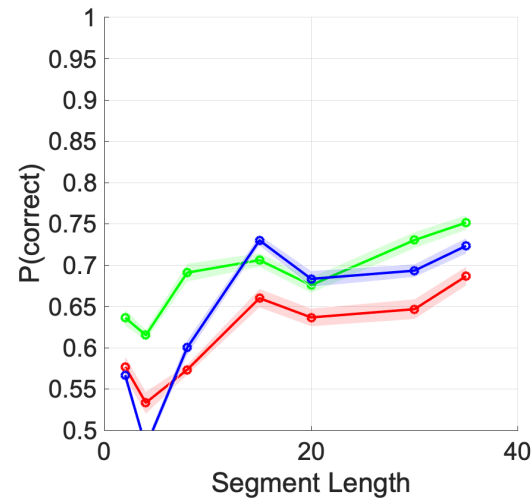
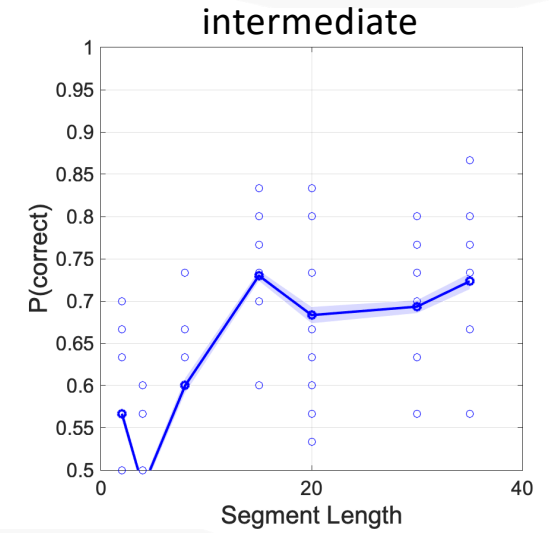
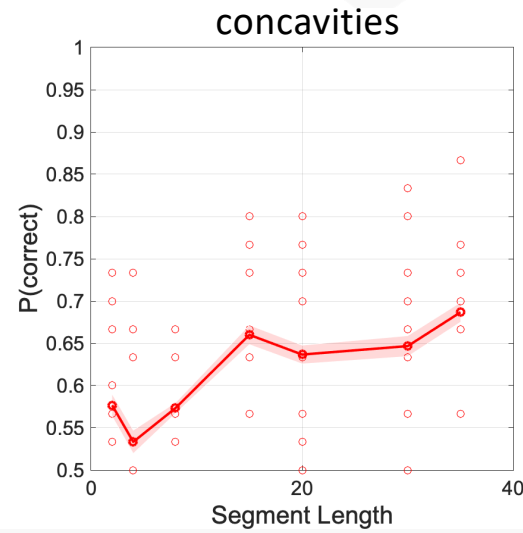
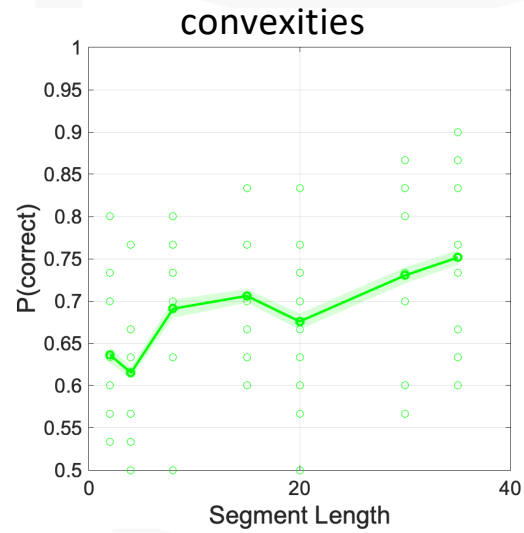
intermediate



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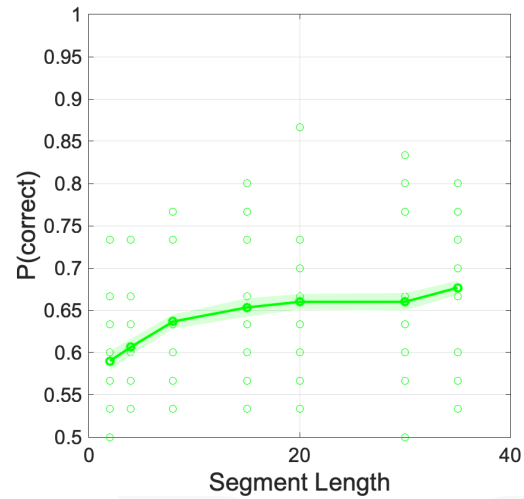


Results – 33% occlusion

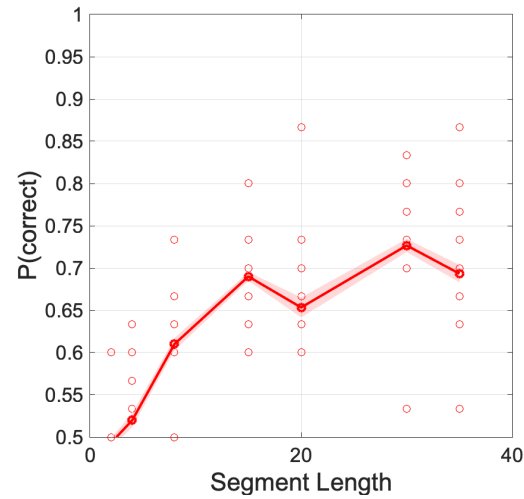


Results – 50% occlusion

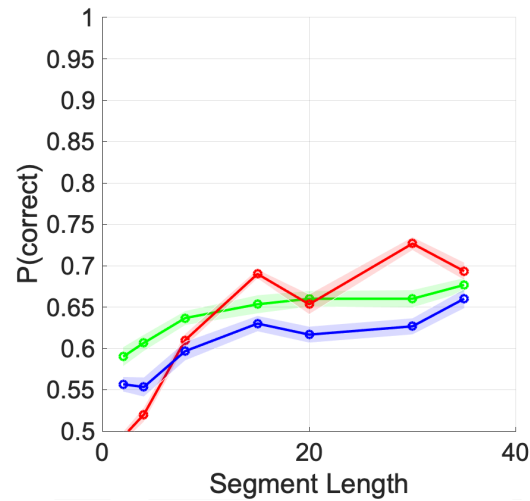
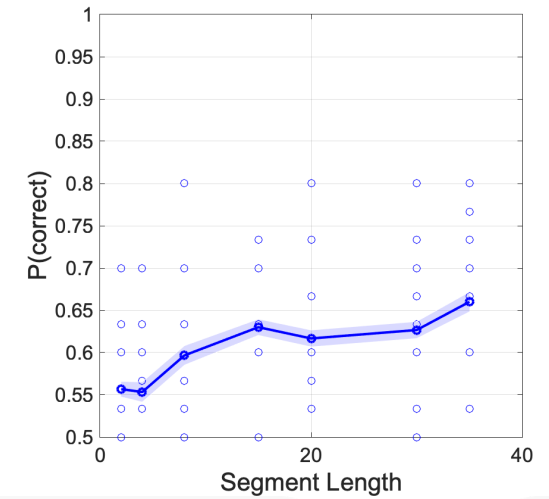
convexities



concavities

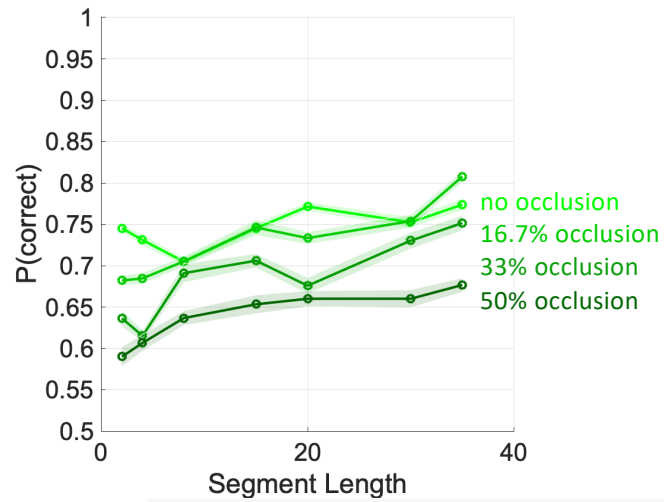


intermediate

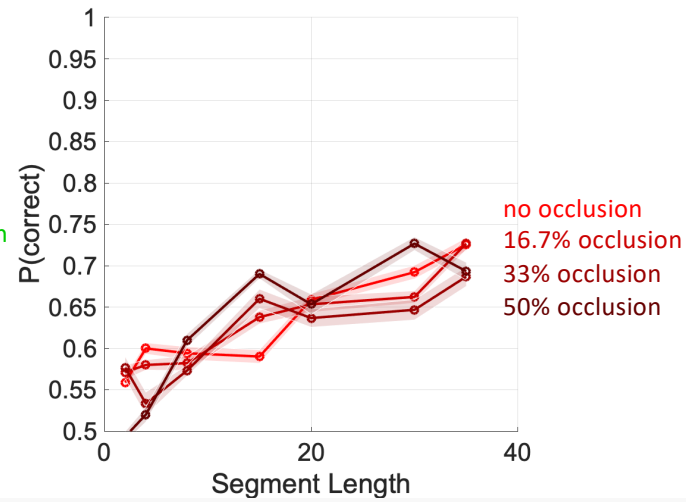


Results – combined

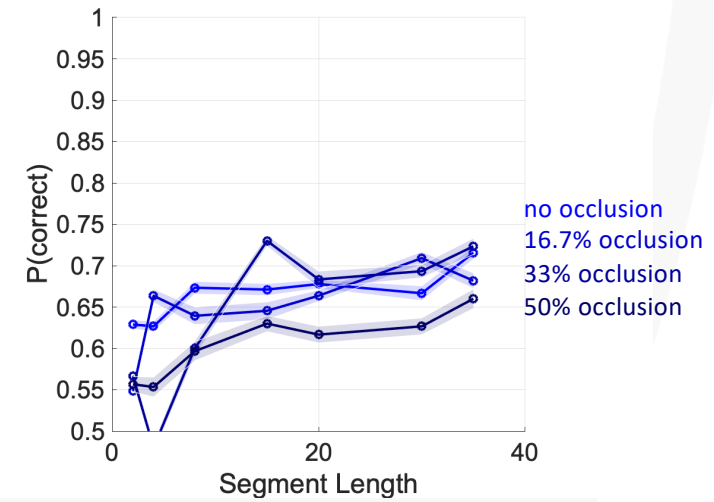
convexities



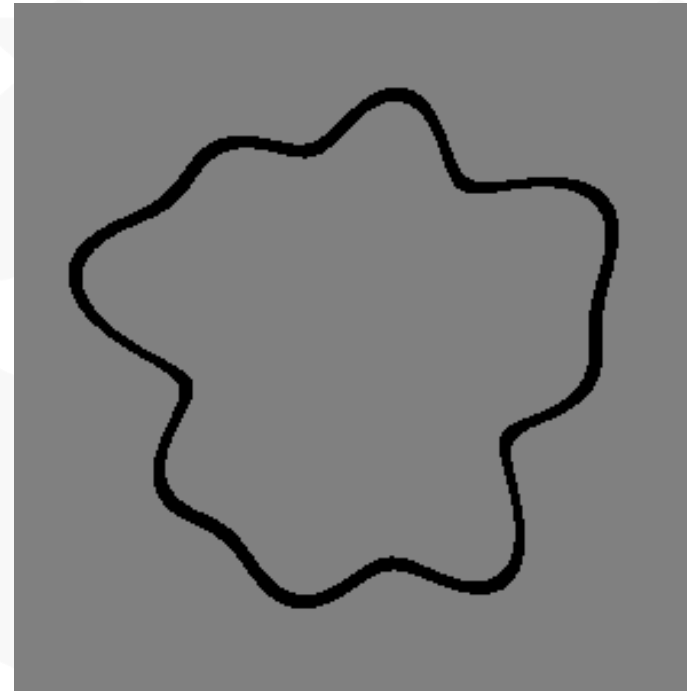
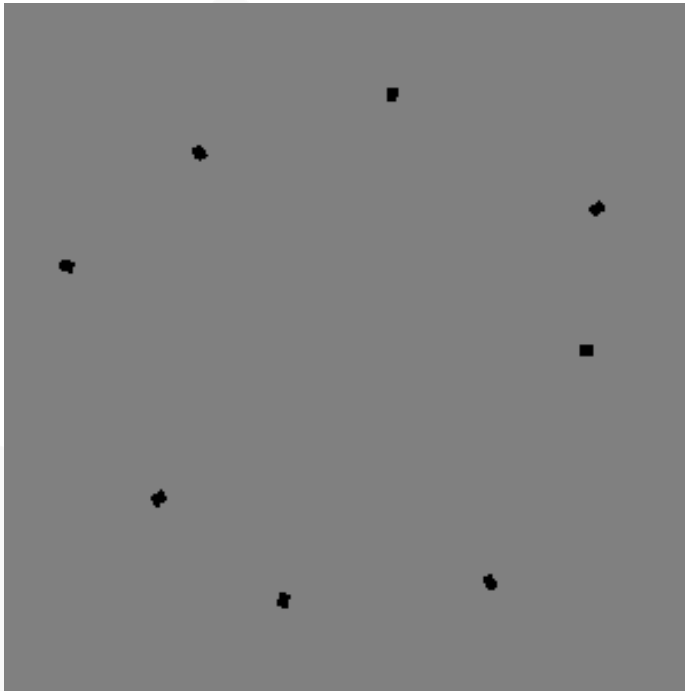
concavities



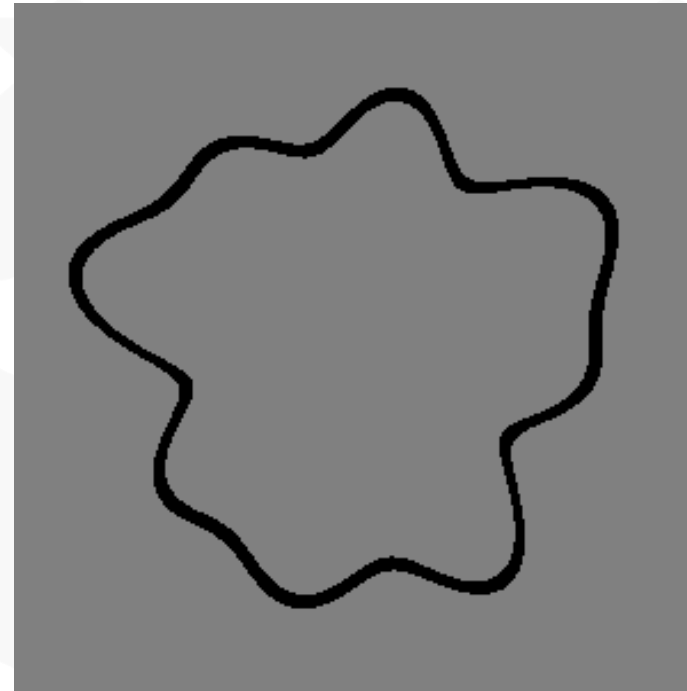
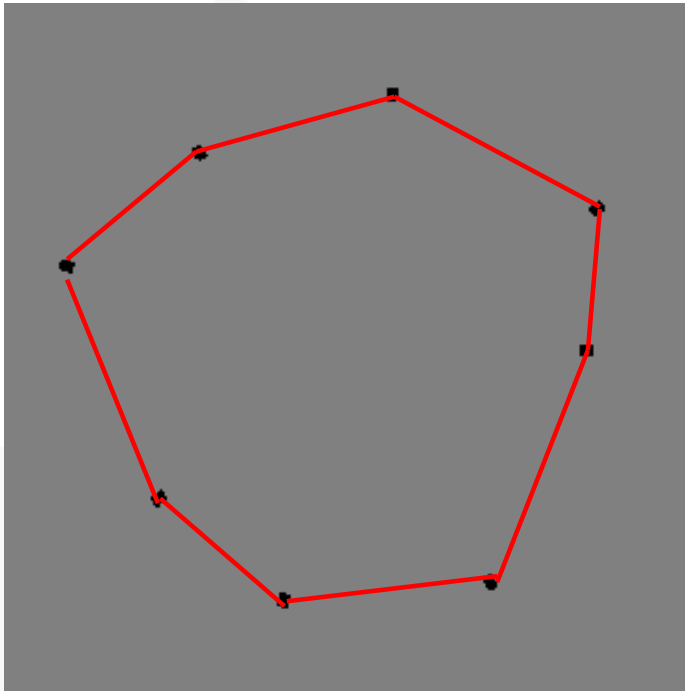
intermediate



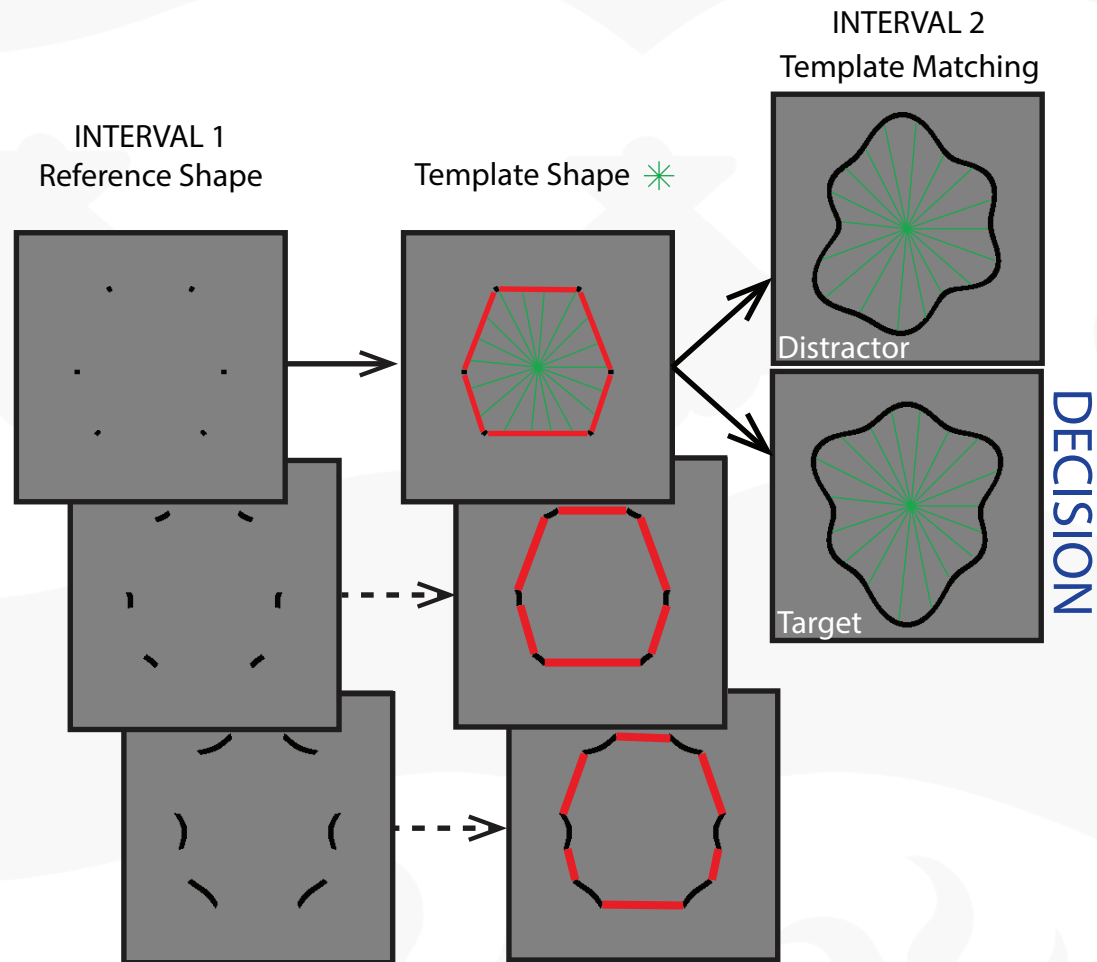
Model – Schmidtmann et al. (2015)



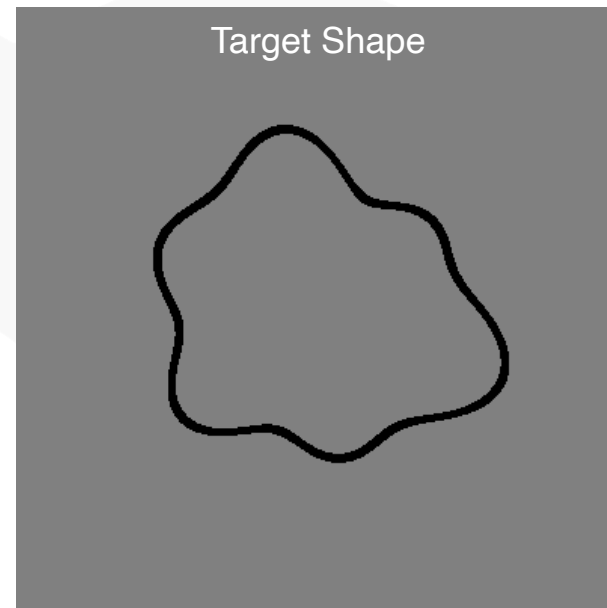
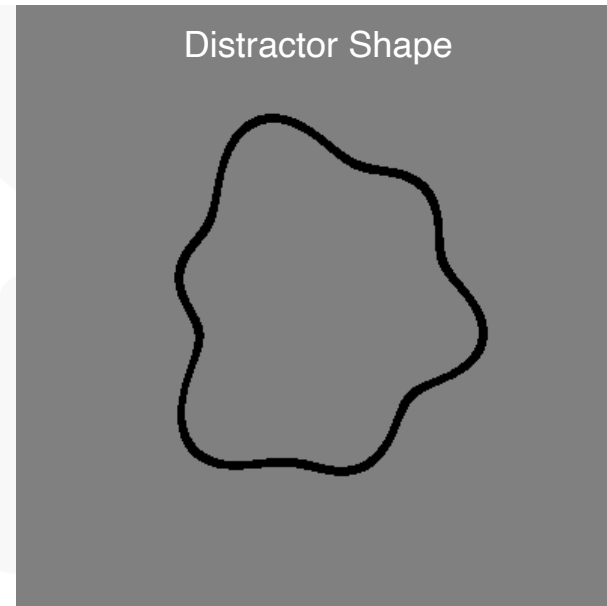
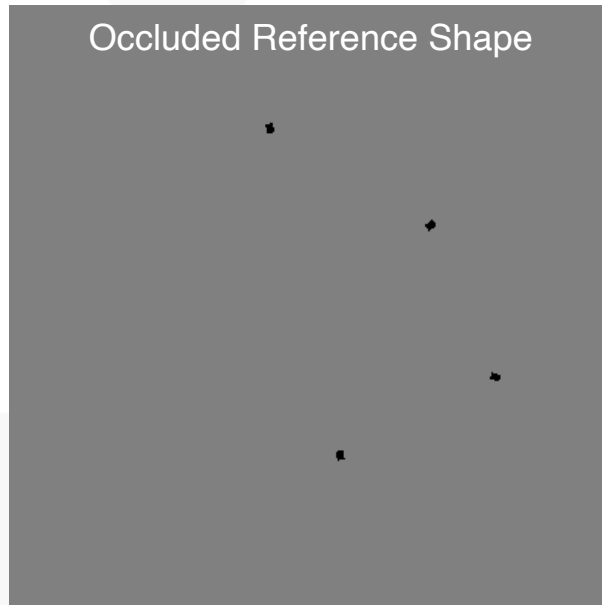
Model – Schmidtman et al. (2015)



Model – Schmidtman et al. (2015)

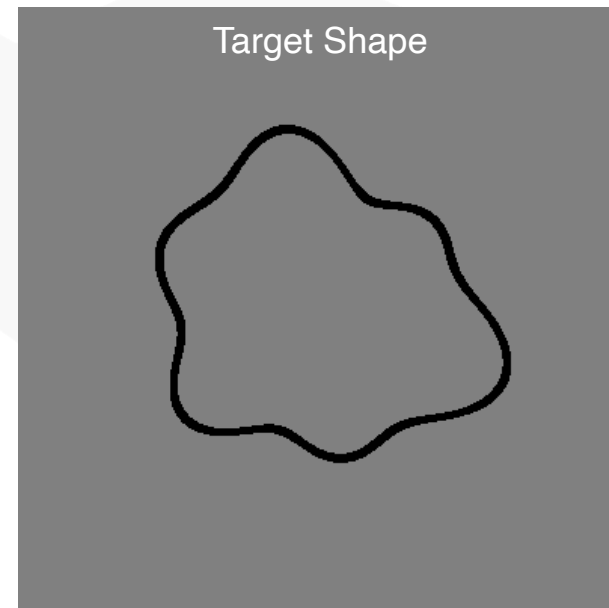
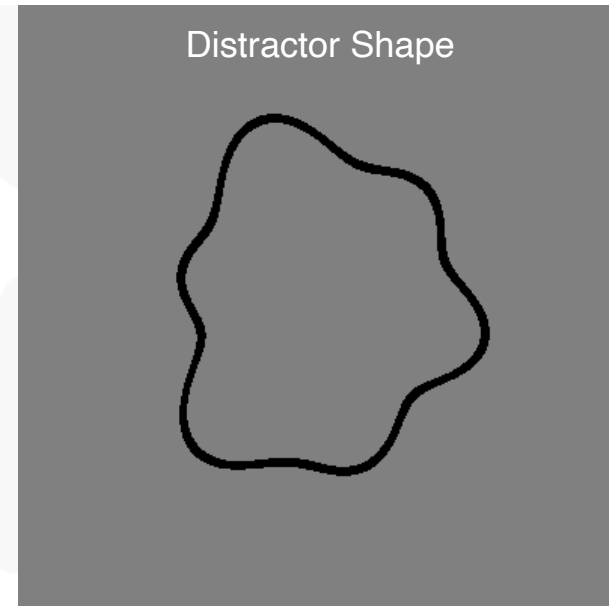
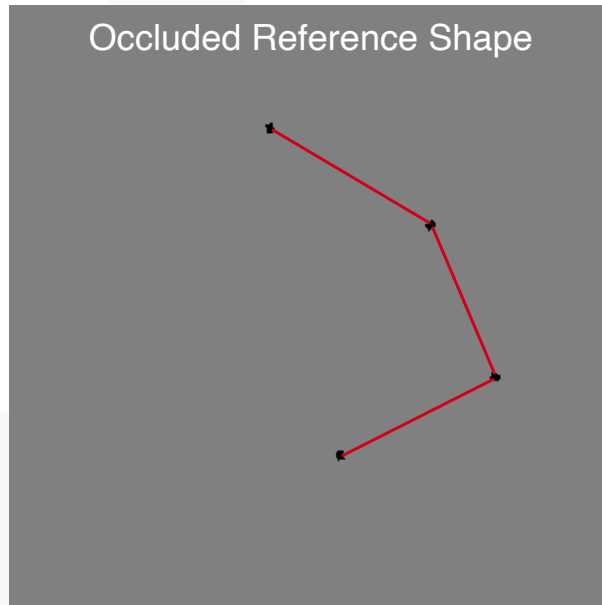


Proposed Model Idea



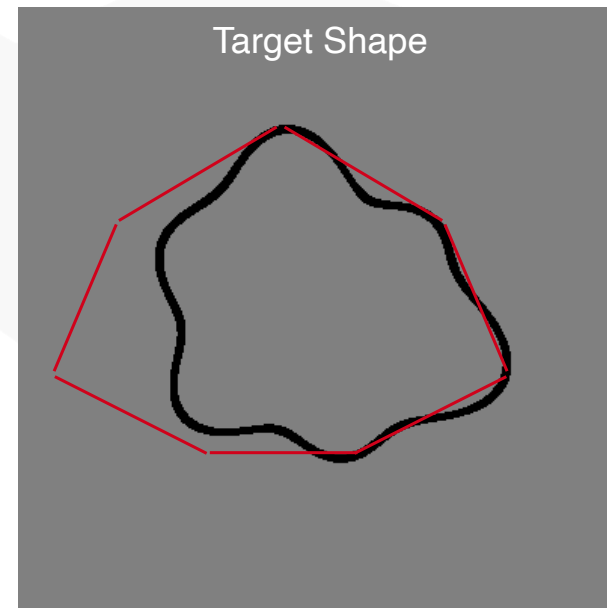
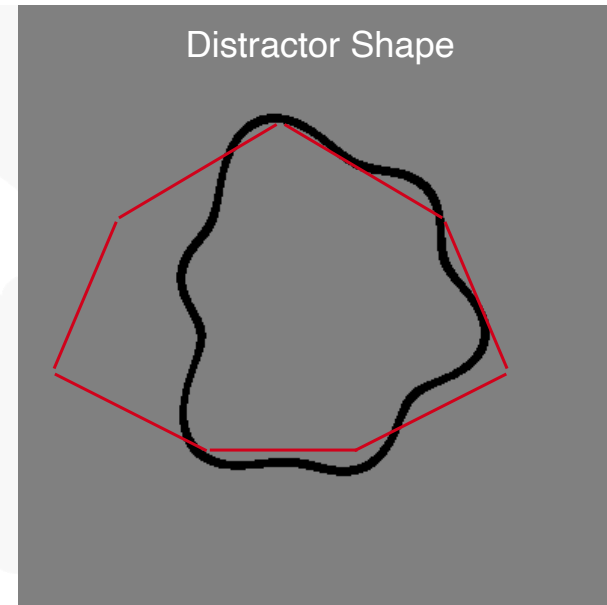
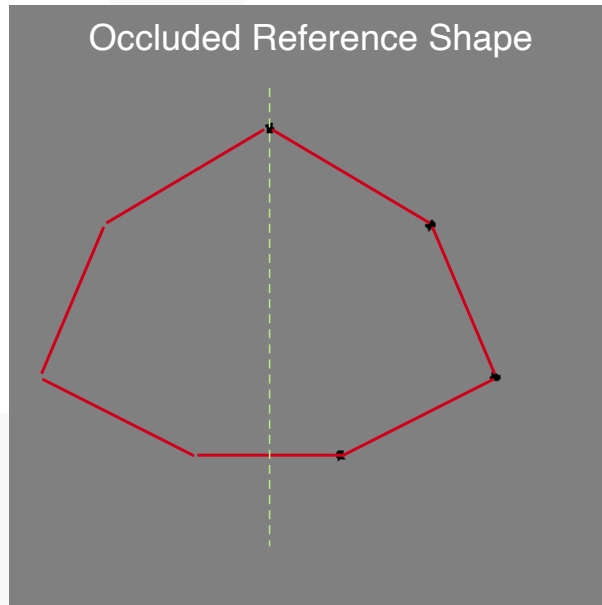
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Proposed Model Idea



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Proposed Model Idea



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Summary

- Performance for convex features is superior to the other shape features and independent of segment length, replicating Schmidtman et al. (2015)
- Points at the location of convex curvature maxima are sufficient to extract shape information
- Performance is only significantly impaired when 50% of the shape is occluded
- Results demonstrate the importance of convexities maxima for shape encoding, and the flexibility of the visual system to deal with partially occluded shapes



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Optometry students (University of Plymouth)

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